

Algorithm for Preliminary Design Optimization of Modern Fishing Vessels.

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Abstract— The making of a Software for optimization design procedure for fishing vessels parameters depend on adequate flow chart and computer program. This work present the flow chat, the formulas and result of a developing QBASIC program based on the presented flow chart for the optimization algorithm for fishing vessels design. This work aim at putting together some of the methods of fishing vessels design presented by the author as well as other authorities concerning obtaining the optimum preliminary design of fishing vessels.

Index Terms— Fishing, vessels, design, logical, lateral, thinking, flowchart, formulas, QBASIC, optimization, program.

1 INTRODUCTION

Methods of preliminary design of fishing vessels are based on owner requirements mainly fish hold capacity, trial speed, endurance, main power amongst others. These methods include the following:

The substitution method basing on empirically derived formulas from which the design vessel parameters are derived by systematic substituting the owner requirements in the formulas [1]. This process yields one design option- the statistical Regression Best Fit (RBF) according to regression analysis for which the formulas were derived. Typically exemplified by references [1],[2],[3] and others.

The iterative method where conflicting owner requirement variables limited by constraints serve as input. This is the case when deadweight range, length range or engine power range are given by the owner [4],[5]. In this case a discrete stepwise range of these parameters are substituted in the empirical equations iteratively so as to get the projected design which satisfy the bounds stipulated by the owners. This method could yield one or more results of the projected vessel parameters. In some cases one or more of the bounds may be modified in other to get some rational results.

The optimization method which involves the two methods above mentioned including a stepwise increment in

the optimized ship parameter objective function and recalculation processes in the other ship constraint functions to obtain the optimum (maximized or minimized) set of ship dimensions [6], [7], [8],[9]. The model of optimization could be linear (Simplex), non-linear, based on single or multiple objective functions, and bounded by equality or inequality defined functions. These functions are defined by the formulas that characterize the design process. The projected vessel parameters from this process will be the optimum option provided all the boundary constraints are well formulated. This method can yield the optimum alternative projected design that satisfied the objective function, the equality and inequality constraints.

The flow chat presented here involves iterative substitution optimization methods. The empirical formulas or rational equations that are derived mainly by regression analysis and by ship design principles are utilised as the system expressions. The constraints are the parametric limits of the formulas used and vessel performance constraints like vessel stability criteria, and freeboard limits.

A developing QBASIC computer program is written based on the presented flow chat. Detailed listing of the QBASIC program is presented. A validation result from the program is presented in Table 1. The major empirical formulas used in the program are clearly presented inside the program. Apart from References listed above, other publications where these and many more empirical formulas related fishing vessels design are [10], [11], amongst others.

Output from the program must meet with the criteria for required minimum stability, freeboard and deck wetting [12], stipulated by International Maritime Organization or others [13]

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2. MATERIALS AND BACKGROUNDS.

2.1 Background Material for the Boat Design Flowchart

The fishing vessel design procedures are presented by the authorities cited above. In this work a new methods involving lateral thinking approach following Edward de Bono's work [14] is applied. This is coupled with the well-known optimization approach. The author used QBASIC program language in other to express the method in an easy to understand way. The main input expressions are some of the empirical formulas presented by the relevant references already mentioned above.

The algorithm adopts a categorization of decision making procedure classified as:

Logical or vertical thinking decision guided by the logical-truth table yielding "true" or "false", "1" or "0" result and well adopted by all computer programming languages and, **Lateral** thinking decision making method which is associated with the new word "po" coined by Edward de Bono. Po means neither yes or no, true or false, 1 or 0, go or stop.

Po means, create, search and generate all possible alternative design, features or characteristics which satisfy the goals and constraints using all possible and conceivable methods. The conceivable methods could be structural, non-structural, random, hierarchical or otherwise, linear, or none linear, discrete, continuous, arbitrary, intuitive, sequential or otherwise provided it predict all alternative design parameters of the designed ship which can safely satisfy the required demands.

Where the vertical (logical) thinking could yields "no" or "yes" results, lateral thinking can yield more acceptable results (basing on any method, any other knowhow or anywhere), from which the optimal result may emerge. In both thinking the desired optimal result is the parameters which best satisfy all the essential design constraints in consideration of the alternative trade-offs or trade-ins necessary to achieve the best option.

The resulting flow chat for the fishing vessels design presented below utilise both lateral thinking and logical thinking in its methodology. The conventional flow chart and even the computer programming languages are design very much on the bases of logical thinking, but the lateral thinking method is introduced here in this work as well. However, we indicate that modern developments in computer programming such as the Object Oriented Programming methods try to adopt some aspects of the lateral thinking philosophy

2.2 The Boat Design Flowchart.

The author created the flow chart on the bases of the creative or lateral as well as logical thinking and optimization method. This is shown in Fig 1. below. The lateral thinking "po" is in-

troduced as the fourth arm after the logical "yes" or "no" branches of the decision test box. The designer experience data are values taken from existing vessels and are explained in the program at the input in line 2010 to 2200 below. In the main process box are the expressions comprising of:

- The substitution of owner requirement input to the empirical regression formulas for the regression best fit RBF design vessel dimensions.
- The iterative stepwise calculation basing on the RBF prediction and on the objective function of the optimization process.
- The checking of the predicted vessel dimensions for conformity with constraints such as safety, freeboard. X is the equality and inequality regression functions of the dimension of fishing vessels. Where L, B, D, d and F are the vessels length Breadth, depth, draft, and freeboard respectively then $X = (L, B, D, d, F \dots)$ the vector of design vessel dimension variables clearly defined in the program below in section 2.3. The results emanating from the algorithm are the dimensions of all possible alternative vessels which can satisfy the owner requirements, the safety and other design criteria which are also included in the program. The developing computer program has an input and output result shown below in section 2.3. The choice of QBASIC is to achieve universal easy understanding of the program pedagogically and otherwise. The input variables, mathematical and logical expressions, as well as the output procedures are presented in the program. A basic knowledge of BASIC programming language is required.

2.3 The Computer Program

The listing of the actual computer program written by the author basing on the flow chart shown in fig 1 is shown below. The program runs on Microsoft DOS QBASIC environment which is the easiest interpreter to be understood by the widest populace in arts, science and engineering.. The program will be re-written in any other computer language as it develops further.

The input variables to the program are explained and listed in the program line 3960 to 4084 for the owner requirement and lines 2350 to 3630 for the vessel operational and masses data. In line 650 the stepwise iteration process started and loops at line 3620 . A maximum of 50 iterations is allowed for this iterative loop by the program for a particular input variables set. Actual number of iterations can be varied by the user, but the program displays result of authentic feasible results which could be any number less than 50 results. The program is for the design of fish vessels limited between 15 to 50m in length. Owner requirement inputs which predict lengths or parameters outside this range cannot be designed by this program.

The program prints the feasible result on the monitor screen and saves the result on files names SFVLESS and SVALT -see line 2830 named SUBROUTINE PRIVES.

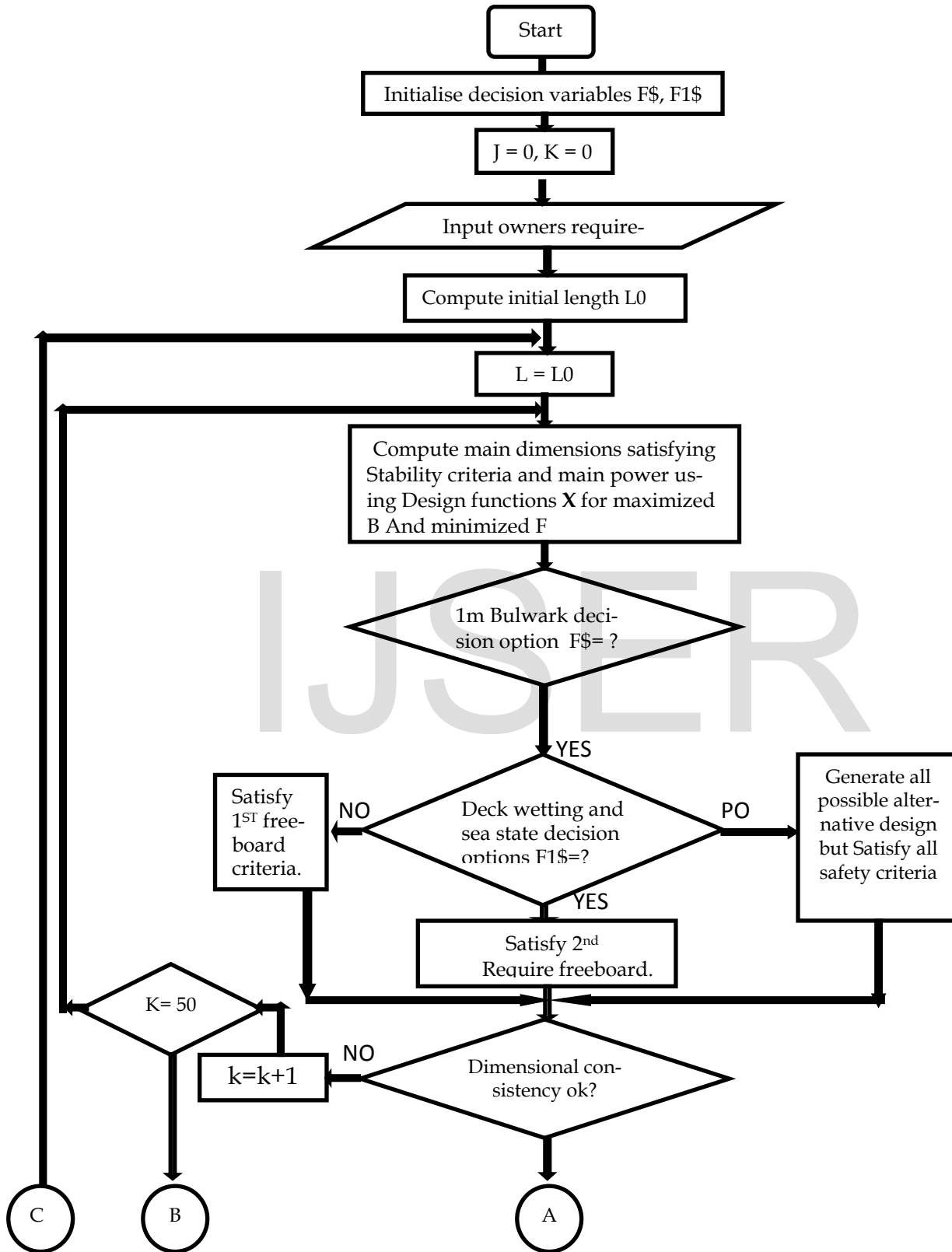


FIG 1. VESSEL DESIGN OPTIMIZATION FLOW CHART

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Table 1. Output result of the program SFVES (stored in sequential file named SVALT anD SFVESH)

***** OWNERS REQUIREMENT *****										
FISH HOLD CAPACITY VH(M^3)	=	131.6								
ENDURANCE AT SEA H(HRS)	=	480								
NUMBER OF CREW + OFFICERS	=	12								
SHIPS TRIAL SPEED V1 (KNOTS)	=	10.5								
LEAST SQUARE FIT LBd(M^3)	=	589.489								
PROGRAM SFVES IS VALID FOR VESSELS OF LENGTH BETWEEN PERPENDICULARS LPP = 15M TO 50 M										
N	1.00	2.00	3.00	4.00	5.00	6.00	7.00	8.00	9.00	10.00
L(M)	26.22	26.72	27.22	27.72	28.22	26.22	25.72	25.22	24.72	24.22
B(M)	7.76	7.84	7.91	7.97	8.03	7.76	7.68	7.59	7.49	7.33
d(M)	2.90	3.01	3.04	3.07	3.09	2.90	2.98	3.08	3.08	3.04
D(M)	3.81	3.84	3.88	3.91	3.94	3.81	3.77	3.72	3.67	3.62
CB	0.52	0.53	0.53	0.54	0.54	0.52	0.52	0.52	0.51	0.51
DISP(T)	316.41	341.39	356.49	371.46	386.30	316.41	314.10	311.71	299.05	282.45
LPP/B	3.38	3.41	3.44	3.48	3.51	3.38	3.35	3.32	3.30	3.28
B/d	2.68	2.60	2.60	2.60	2.60	2.68	2.57	2.46	2.43	2.43
LBd	589.49	631.53	654.96	677.97	700.57	589.49	589.49	589.49	570.04	542.84
LBB(M^3)	774.87	805.31	835.19	864.53	893.33	774.87	743.86	712.27	680.10	647.34
B/D	2.04	2.04	2.04	2.04	2.04	2.04	2.04	2.04	2.04	2.04
F/B	0.12	0.11	0.11	0.11	0.11	0.12	0.10	0.08	0.08	0.08
P(KW)	508.37	525.03	541.68	558.33	574.98	508.37	491.72	475.07	458.41	441.76
P/V(KW/Kn)	48.42	50.00	51.59	53.17	54.76	48.42	46.83	45.24	43.66	42.07
GRT	141.87	147.13	152.39	157.66	162.92	141.87	136.61	131.34	126.08	120.82
F(M)	0.91	0.83	0.84	0.84	0.85	0.91	0.78	0.64	0.59	0.58
F1	0.78	0.81	0.82	0.82	0.82	0.78	0.82	0.86	0.87	0.87
F2(M)	1.33	1.38	1.39	1.40	1.42	1.33	1.37	1.41	1.41	1.39
GM(M)	0.76	0.78	0.79	0.79	0.79	0.76	0.79	0.82	0.83	0.83
MS	92.63	97.23	100.95	104.63	108.30	92.63	90.10	87.58	84.09	80.21
MO	56.18	58.26	60.33	62.40	64.47	56.18	54.11	52.03	49.95	47.86
MM	11.07	11.34	11.61	11.88	12.14	11.07	10.80	10.52	10.24	9.96
MF	64.76	64.76	64.67	64.76	64.76	64.76	64.76	64.76	64.76	64.76
ML	6.51	6.72	6.93	7.15	7.36	6.51	6.30	6.09	5.87	5.66
MW	89.86	89.86	89.86	89.86	89.86	89.86	89.86	89.86	89.86	89.86
MSA	48.00	48.00	48.00	48.00	48.00	48.00	49.00	48.00	48.00	48.00
MP	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00
MCOB	1.56	1.56	1.56	1.56	1.56	1.56	1.56	1.56	1.56	1.56
DWT	354.28	370.43	390.49	415.44	446.47	484.02	531.65	591.05	665.12	757.46
DISP2	171.08	171.08	171.08	171.08	171.08	171.08	171.08	171.08	171.08	171.08
DWT-BAL	0.41	0.46	0.47	0.48	0.48	0.30	0.27	0.24	0.19	0.15
HBMIN	3.43	3.51	3.58	3.65	3.73	3.43	3.36	3.29	3.22	3.15
RBF										
Mopt										
Miopt										

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